

From Boltzmann to

Euler:

Hilbert's 6th Problem

Revisited

M. Slemrod

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I. BOLTZMANN EQUATION AND
EXTENDED THERMODYNAMICS
(see C.M. Dafermos, Hyp. Cons. Laws. 3rd edition)

In contrast to continuum mechanics

kinetic theories approach matter

as an ensemble of interacting
molecules. The state of the

system is realized probabilistically

(which was revolutionary view of

Maxwell for equilibrium configuration

and Boltzmann for the full dynamics)

Of course this probabilistic approach

was later continued by Schrodinger

in his approach to quantum mechanics

In kinetic theory as noted above
the state may be written as a
molecular density function

$$f(\xi, x, t)$$

of the velocity $\xi \in \mathbb{R}^3$ of molecules occupying
at position $x \in \mathbb{R}^3$ and at time t . Hence f
is the probability of finding a molecule with velocity ξ at point x
and time t .

In classical kinetic theory of
monatomic gases, $f(\xi, x, t)$
satisfies the Boltzmann equation

$$\partial_t f + \xi \cdot \text{grad}_x f = Q(f) \quad (1.1)$$

where Q stands for a complicated
collision integral operator.

Notice the Boltzmann equation
when $Q \equiv 0$ just gives the
free transport of particles moving
with velocity ξ , whereas if

If f is independent of x the equation is just a space homogeneous equation

$$\partial_t f = Q(f) \quad (1.2)$$

only accounting for collisions but not transport.

Some useful results for operator Q are as follows.

Collision invariants

$$\int_{\mathbb{R}^3} Q(f) \varphi(\xi) d\xi = 0 \quad (1.3)$$

if and only if a linear combination of

$$\left\{ \begin{array}{l} \psi_0 = 1, \\ (\psi_1, \psi_2, \psi_3) = \xi, \\ \psi_4 = |\xi|^2. \end{array} \right.$$

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i.e.

$$\int Q(f) (a + \underline{b} \cdot \underline{\xi} + c|\underline{\xi}|^2) d\underline{\xi} = 0 \quad (1.4)$$

for all $a \in \mathbb{R}$, $\underline{b} \in \mathbb{R}^3$, $c \in \mathbb{R}$ constants.

Solution of the equation $Q(f) = 0$

$$Q(f) = 0 \Leftrightarrow$$

$$f(\underline{\xi}) = \exp(a + \underline{b} \cdot \underline{\xi} + c|\underline{\xi}|^2)$$

Set $c = -\alpha$, $\alpha > 0$ (to force

f to be in $L^1(\mathbb{R}^3)$ as a function of $\underline{\xi}$),

$\underline{b} = 2\alpha \underline{v}$. Then

$$a + \underline{b} \cdot \underline{\xi} + c|\underline{\xi}|^2 = a + 2\alpha \underline{v} \cdot \underline{\xi} - \alpha|\underline{\xi}|^2$$

$$= -\alpha (\underline{\xi} - \underline{v}) \cdot (\underline{\xi} - \underline{v}) + \alpha \underline{v} \cdot \underline{v} + a$$

and

$$\begin{aligned}
 f(\xi) &= \exp(a + \underline{b} \cdot \xi + c|\xi|^2) \\
 &= A \exp(-\alpha(\xi - \underline{v})(\xi - \underline{v})), \quad \text{i.e.}
 \end{aligned}$$

$$f(\xi) = A \exp(-\alpha|\xi - \underline{v}|^2) \quad (1.5)$$

and A, α, \underline{v} denote a

new set of five arbitrary constants.

Hence the solution (1.5) of

$Q(f) = 0$ is the classical

Maxwellian distribution.

Moments of Boltzmann equation

The formal connection between the continuum and kinetic theories of gas dynamics can be seen by considering the family of moments of f :

$$\#_{i_1 i_2 \dots i_N} = \int_{\mathbb{R}^3} \xi_{i_1} \dots \xi_{i_N} f d\xi, \quad (1.6)$$

$$i_1 = 1, 2, 3, \quad i_2 = 1, 2, 3,$$

$$\dots \quad i_N = 1, 2, 3.$$

To derive the dynamics of moments we multiply the Boltzmann

equation by $1, \underbrace{\xi_1, \xi_2, \xi_3}_{\xi_i}, \underbrace{\xi_1 \xi_1, \xi_1 \xi_2, \dots}_{\xi_i \xi_j},$

etc.

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$$\int_{\mathbb{R}^3} \left(\begin{array}{c} 1 \\ \xi_i \\ \xi_i \xi_j \\ \xi_i \xi_j \xi_k \\ \vdots \\ \xi_i \xi_j \xi_k \dots \xi_l \end{array} \right) \left(\int_{\mathbb{R}^3} f + \xi \cdot \text{grad}_x f - Q(f) \right) d\xi = 0$$

Let us compute the first few moments explicitly.

Zeroth moment:

$$\int_{\mathbb{R}^3} Q(f) d\xi + \int_{\mathbb{R}^3} \xi \cdot \text{grad}_x f d\xi = 0$$

since (1.3) implies $\int_{\mathbb{R}^3} Q(f) d\xi = 0$.

But $\xi \cdot \text{grad}_x f = \xi_i \partial_{x_i} f = \partial_{x_i} (\xi_i f)$

where $\xi_i \partial_{x_i} = \sum_{i=1}^3 \xi_i \partial_{x_i}$,

i.e. repeated indices mean summation.

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Hence

$$\partial_t \int f d\xi + \partial_{x_i} \int_{\mathbb{R}^3} (\xi_i f) d\xi = 0$$

or in terms of (1.6)

$$\partial_t F + \partial_i F_i = 0$$

First moments:

$$\int_{\mathbb{R}^3} \xi_i \partial_t f d\xi + \int_{\mathbb{R}^3} \xi_i \xi_j \text{grad}_x f d\xi = 0$$

where again we used (1.6). Write

$$\begin{aligned} \xi_i \xi_j \text{grad}_x f &= \xi_i \xi_j \partial_{x_j} f \\ &= \partial_{x_j} (\xi_i \xi_j f) \end{aligned}$$

and we see

$$\partial_t F_i + \partial_j F_{ij} = 0$$

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Second moments

Following the same procedure we see the second moments satisfy

$$\partial_x F_{ij} + \partial_{x_k} F_{ijk} = P_{ij}$$

where

$$P_{ij} = \int_{\mathbb{R}^3} \xi_i \xi_j Q(\xi) d\xi.$$

Notice unlike the zeroth and first moments P_{ij} is not identically

zero but via (1.6) the

trace $\underline{P} = P_{ii}$ is zero. Thus

we do have the relation

$$\partial_x F_{ii} + \partial_{x_k} F_{iik} = 0$$

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If we continue taking moments we obtain the infinite system of evolution equations

$$\partial_t F + \partial_i F_i = 0 \quad (i=1,2,3)$$

$$\partial_t F_i + \partial_j F_{ij} = 0 \quad (i,j=1,2,3)$$

$$\partial_t F_{ij} + \partial_{x_k} F_{ijk} = P_{ij} \quad (i,j,k=1,2,3)$$

$$(\partial_t F_{ii} + \partial_{x_k} F_{iik} = 0)$$

$$\partial_t F_{ijk} + \partial_l F_{ijkl} = P_{ijk}$$

⋮

$$\partial_t F_{i_1 \dots i_N} + \partial_{x_m} F_{i_1 \dots i_N, m} = P_{i_1 \dots i_N}$$

$$(i_1, \dots, i_N = 1, 2, 3)$$

(1.7)

Since f represents the
 (probabilistically) the density of
 molecules moving with velocity ξ
 at point x at time t , the integral

$$F(x,t) = \int_{\mathbb{R}^3} f(\xi, x, t) d\xi = f(x,t)$$

would be the density of molecules at
 point x and time t .

Similarly we write

$$F_i = \int f v_i, \quad i=1,2,3, \quad (1.8)$$

$$F_{ij} = \int f v_i v_j - T_{ij}, \quad i,j=1,2,3, \quad (1.9)$$

$$\frac{1}{2} F_{ii} = \int f \epsilon + \frac{1}{2} \int f |v|^2, \quad (1.10)$$

$$\frac{1}{2} F_{iix} = \left(\int f \epsilon + \frac{1}{2} \int f |v|^2 \right) v_x - T_{ix} v_i + q_x, \quad x=1,2,3. \quad (1.11)$$

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Notice we have the identifications

$$\rho = F$$

$$v_i = \frac{F_i}{\rho}$$

$$T_{ij} = -F_{ij} + \rho v_i v_j$$

$$\mathcal{E} = \frac{1}{2} \frac{F_{ii}}{\rho} - \frac{1}{2} |v|^2,$$

$$q_k = \frac{1}{2} F_{iik} - \left(\rho \mathcal{E} + \frac{1}{2} \rho |v|^2 \right) v_k + T_{ki} v_i$$

and each macroscopic quantity:
($\rho, v_i, T_{ij}, \mathcal{E}, q_k$) representing
(density, velocity, Cauchy stress, internal
energy, heat flux) can be
expressed in terms of the
moments of F .

Let us rewrite the Cauchy stress
as a superposition of two parts:

$$T_{ij} = -p \delta_{ij} + \sigma_{ij}$$

(1.13)

where trace $\sigma = \sigma_{ii} = 0$.

Then we see

$$T_{ii} = -p \delta_{ii} = -3p.$$

But from (1.12)

$$\left\{ \begin{array}{l} T_{ii} = -F_{ii} + \rho v^2 \\ \epsilon = \frac{1}{2} \frac{F_{ii}}{\rho} - \frac{1}{2} v^2 \end{array} \right.$$

$$\text{so } 2\rho\epsilon = F_{ii} - \rho v^2$$

and

$$T_{ii} = -2\rho\epsilon - \rho v^2 + \rho v^2, \text{ i.e.}$$

$$T_{ii} = -2\rho\epsilon \quad (1.14)$$

Substitute (1.14) into (1.13):

$$\begin{aligned} T_{ii} &= -p \delta_{ii} + \sigma_{ii} \\ &= -3p \end{aligned} \Rightarrow$$

$$-2p \epsilon = -3p$$

$$\frac{3}{2} p = p \epsilon$$

(1.15)

Of course (1.15) is the form of familiar constitutive equation of a polytropic gas

$$\epsilon = c f^{\gamma-1} e^{s/c}, \quad p = R f^{\gamma} e^{s/c}, \quad \theta = f^{\gamma-1} e^{s/c}$$

s specific entropy, θ temperature

~~.....~~

$$e^{5/c} = \frac{\epsilon}{c} \rho^{1-\gamma}$$

$$p = R \rho^\gamma \frac{\epsilon}{c} \rho^{1-\gamma}$$

$$p = \frac{R \epsilon \rho}{c}$$

$$\frac{R}{c} = \frac{2}{3} \quad (\text{where } \gamma = 5/3)$$

More familiar perhaps is writing
the relations in terms of θ

$$\epsilon = c \theta,$$

$$p = \frac{R \rho^\gamma \theta}{\rho^{\gamma-1}} = R \rho \theta,$$

i.e. internal energy is proportional to
temperature, and pressure
is proportional to density times
temperature.

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Truncation of the moment hierarchy (1.7) will result in a finite number of equations.

But the resulting system will not be closed.

This is because of two facts:

(i) there is always a flux of one higher moment appearing in each truncation and

(ii) the production term P_{ij} , P_{ija} , ... etc. (except for P_{ii}) are undetermined.

Extended thermodynamics is a theory that closes the system by postulating a closure of

(i) the higher moment flux

(ii) the undetermined production terms

in terms of the lower moments.

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This program was initiated by
H. Grad and developed in more
recent years by J. Müller and his
collaborators (see J. Müller, T. Ruggeri,

Rational Extended Thermodynamics).

Let us consider the simplest
case: truncation at 5 moments.

$$\partial_x F + \partial_c F_c = 0$$

$$\partial_x F_c + \partial_j F_{ij} = 0$$

$$\partial_x F_{ii} + \partial_{ik} F_{iik} = 0$$

(1.16)

Here there is no need to
postulate production terms since they
have all vanished.

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In terms of macroscopic dependent variables we write our system (1.16) as

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$$\partial_t \rho + \partial_i (\rho v_i) = 0$$

$$\partial_t (\rho v_i) + \partial_j (-T_{ij} + \rho v_i v_j) = 0 \quad (1.17)$$

$$\partial_t (2\rho \epsilon + \rho |v|^2)$$

$$+ \partial_k (2q_k + 2T_{ki} v_i + 2\rho \epsilon v_k + \rho |v|^2 v_k) = 0$$

But recall

$$T_{ij} = -p \delta_{ij} + \sigma_{ij}, \quad \text{with}$$

$$\sigma_{ii} = 0,$$

and $\frac{3}{2} p = \rho \epsilon.$ Hence we

can write (1.17) as

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$\partial_t \rho + \partial_i (\rho v_i) = 0$	<u>1 equ</u>
$\partial_t (\rho v_i) + \partial_j (\rho v_i v_j + p \delta_{ij}) = \partial_j \sigma_{ij}$	<u>3 eqns</u>

$$\left\{ \begin{aligned} &\partial_t \left(\frac{1}{2} \rho |v|^2 + \rho \epsilon \right) \\ &+ \partial_k \left(\rho v_k - T_{ki} v_i + \rho \epsilon + \frac{1}{2} \rho |v|^2 v_k \right) = 0 \end{aligned} \right.$$

⇓

$\partial_t \left(\frac{1}{2} \rho v ^2 + \rho \epsilon \right)$	<u>1 equ</u>
$+ \partial_k \left(-(\rho v_k) + \rho \epsilon + \frac{1}{2} \rho v ^2 v_k \right)$	
$= -\partial_k \rho v_k + \partial_k \sigma_{ki} v_i$	

with $\frac{3}{2} p = \rho \epsilon$

5 eqns in Total

Conservation of
Mass, Momentum, Energy.

$$1 + 3 + 1 = 5$$

Unknowns

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$$\rho, v_i, \epsilon \text{ (or } p \text{)}$$

plus

q_k

$$k = 1, 2, 3$$

(3 unknowns)

σ_{ij}

$$\begin{pmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ \sigma_{12} & \sigma_{22} & \sigma_{23} \\ \sigma_{13} & \sigma_{23} & \sigma_{33} \end{pmatrix}$$

(5 unknowns)

$$\sigma_{11} + \sigma_{22} + \sigma_{33} = 0$$

The simplest closure is to take these left over unknowns to be identically zero.

This yields the Euler equations of compressible gas dynamics.

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The next level of closure is to use the first three equations of (1.7)

$$\partial_t F + \partial_i F_i = 0 \quad 1 \text{ eqn}$$

$$\partial_t F_i + \partial_j F_{ij} = 0 \quad 3 \text{ eqns}$$

$$\partial_t F_{ij} + \partial_n F_{ijn} = P_{ij} \quad 6 \text{ eqns}$$

and extract 3 more equations from

$$\partial_t F_{ijk} + \partial_n F_{ijnk} = I_{ijk}$$

by contracting on two of the indices

$$\text{e.g. } i=j.$$

3 eqns

$$1 + 3 + 6 + 3 = 13 \text{ moment eqns}$$

in

$$F, F_i, F_{ij}, F_{ijk}$$

$$1 + 3 + \underbrace{6} + \underbrace{3} = 13 \text{ unknowns.}$$

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Again as before our system will not
be closed. Hence we must impose a

closure rule. The rule suggested by

Muller & Ruggeri is any closure
must produce an "entropy" inequality

$$\partial_t \psi + \partial_i \psi_i \leq 0$$

(ψ convex in the ^{extended} flux variables).

Of course this motivated by the
second law of thermodynamics

when $-\psi$ would be the physical entropy.

The advantage of this approach is

that if ψ is convex then the
underlying system (by a result

of Friedrichs and independently Godunov)

can be made symmetric hyperbolic

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H Grad (1949) suggested a different closure rule: Just assume f is a linear function of number of moments of the truncated system.

Then plug this f into (1.6) to find the coefficients in the linear combination.

Grad's approach yields an "entropy"

inequality only near equilibrium

and hence hyperbolicity may

be lost. In fact hyperbolicity

has been shown to fail away

from equilibrium.

Of course implementation of either closure rule is

an unpleasant computation.

Grad's ~~same~~ ~~for~~ 13 moments equations are in his original paper

(CRAY, 1949) and the

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Müller - Ruggeri 13 moments are in

C.M. Dafermos, 3rd edition, Hyperbolic Cons. Laws,

p.67-68) as well as the book of

Müller & Ruggeri, Rational Extended Thermodynamics,

2nd edition). We

will examine this 13 moment

system in § 2.

2. The Chapman-Eskog expansion

Recall the Boltzmann equation has the form

$$\partial_t f + \mathcal{E} \cdot \text{grad}_x f = Q(f).$$

If we want view the dynamics on

a macroscopic scale it is convenient

to rescale space and time, i.e. set

$$x = \frac{x'}{\mathcal{E}}, \quad t = \frac{t'}{\mathcal{E}}$$

so that the Boltzmann equation becomes

$$\partial_{t'} f + \mathcal{E} \cdot \text{grad}_{x'} f = \frac{Q(f)}{\mathcal{E}}.$$

The parameter \mathcal{E} is Knudsen
number and measures the mean free
 path between collisions. For
 convenience we set drop " , " in
 our equation:

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$$\frac{\partial f}{\partial t} + \epsilon \cdot \text{grad}_x f = \frac{Q(f)}{\epsilon} \quad (2.1)$$

D. Hilbert proposed solving (2.1) as
a formal ~~power~~ asymptotic expansion

$$f(\epsilon, x, t) = f_0(\epsilon, x, t) + \epsilon f_1(\epsilon, x, t) + \epsilon^2 f_2(\epsilon, x, t) + \dots \quad (2.2)$$

which we call the Hilbert expansion.

Obviously balancing orders of ϵ yields

$$Q(f_0) = 0$$

and we know from § 1 that

$$f_0(\xi) = A \exp(-\alpha |\xi - v|^2)$$

but since f_0 may depend on x, t this means

A, α, v can depend on x, t as well:

$$f_0(\xi, x, t) = A(x, t) \exp(-\alpha(x, t) |\xi - v(x, t)|^2)$$

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Recall that the macroscopic density, velocity, and temperature can be related to moments of f :

$$\rho(x, t) = \int f d\xi$$

$$\rho v_i = \int \xi_i f d\xi$$

$$\rho E = \frac{3}{2} \rho R T = \int \frac{1}{2} |\xi - v_0|^2 f d\xi$$

so at order ϵ we can solve for

A, α, v in terms of f, v_i, θ :

$$\alpha = 3(4e)^{-1} = (2R\theta)^{-1}$$

$$A = \left(\frac{4}{3} \pi e \right)^{-3/2} = (2\pi R\theta)^{-3/2}$$

to see

$$f_0(\xi, x, t) = (2\pi R\theta)^{-3/2} \exp\left(-\frac{1}{2} \frac{|\xi - v|^2}{R\theta}\right) \quad (2.2)$$

and the Maxwellian distribution has been written as a function $f_0(\xi, x, t)$ where dependence on x, t appears only through the fluid variables ξ, v, θ .

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Next go back to our five moment

truncation (1.16):

$$\partial_t F + \partial_i F_i = 0$$

(1.16)

$$\partial_t F_i + \partial_j F_{ij} = 0$$

$$\partial_t F_{ii} + \partial_k F_{ikk} = 0$$

From the Hilbert expansion we know f to leading order in ϵ , i.e. f_0 given by (2.2). Hence plugging this Maxwellian

distribution allows us to compute

F, F_i, F_{ij}, F_{ikk} to leading order.

This gives 5 equations in 5 unknowns

ρ, v_i, T , i.e. the Euler equations

of an ideal gas

$$\partial_t f + \partial_i (f v_i) = 0$$

$$\partial_t (f v_i) + \partial_j (p \delta_{ij} + f v_i v_j) = 0$$

$$\partial_t \left(\frac{1}{2} f |v|^2 + p \epsilon \right) + \partial_i \left(- (p \delta_{ij}) + p \epsilon + \frac{1}{2} f |v|^2 v_i \right) = 0 \quad (2.3)$$

$$\frac{3}{2} p = p \epsilon, \quad \epsilon = \frac{3}{2} R \theta.$$

So formally if we write (as Hilbert did)

$$f = f_0 + \epsilon f_1 + \epsilon^2 f_2 + \dots$$

and let $\epsilon \rightarrow 0$, then $f \rightarrow f_0$ and

we have passed from the Boltzmann equations

to its hydrodynamic limit (2.3),

i.e. the compressible Euler equations.

This was certainly a strong

motivation for Hilbert to propose that

this formal derivation be made

rigorous in his 1900 address to

the International Congress of Mathematicians in Paris.

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Closely related to the Hilbert expansion is the Chapman-Eskog expansion which is just the Hilbert expansion written so that dependence (for f) on x, t appears only through the macroscopic fluid variables M

$$M \equiv (\rho, v_i, \theta)$$

and space derivatives of M .

Of course at order 1 there

is no difference between the Hilbert and Chapman-Eskog

expansions. At order ϵ , C-E

for the Boltzmann equation, will deliver

the compressible Navier-Stokes-Fourier (N-S-F)

equations for gas dynamics. This

was a major breakthrough for

the kinetic theory since it

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yielded what is believed to be the $O(\epsilon)$ correction to the Euler equations.

The coefficients for the viscosity and heat conduction terms are consistent with experiment. But logically if the $O(\epsilon)$ term improves Euler, then $O(\epsilon^2)$ should improve (N-S-F). But this turns out to not to be

case. The next level $O(\epsilon^2)$ (Burnett order) yields a system of equations which is unstable to high frequency perturbations of the rest state.

As a way to both understanding the C-F expansion and the issues of instability let us choose a very simple

but useful example: Grad's 13 moment equations.

Again the system has used the scaling

$$x = \frac{x'}{\epsilon}, \quad t = \frac{t'}{\epsilon}$$

and dropped the primes for convenience.

$$(3.3.58) \quad \frac{1}{2}F_{iik} = (\rho\varepsilon + \frac{1}{2}\rho|v|^2)v_k - T_{ki}v_i + q_k, \quad k = 1, 2, 3,$$

the first equation in (3.3.53) renders conservation of mass, the second equation renders conservation of linear momentum, and one half the trace of the third equation renders conservation of energy, for a heat-conducting viscous gas with density ρ , velocity v , internal energy ε , Cauchy stress T and heat flux q . We regard T as the superposition, $T = -pI + \sigma$, of a pressure $p = -\frac{1}{3}T_{ii}$ and a shearing stress σ that is traceless, $\sigma_{ii} = 0$. By virtue of (3.3.56) and (3.3.57),

$$(3.3.59) \quad \rho\varepsilon = \frac{3}{2}p,$$

which is compatible with the constitutive equations (2.5.20) of the polytropic gas, for $\gamma = 5/3$.

Motivated by the above observations, one may construct a full hierarchy of continuum theories by truncating the infinite system (3.3.53), retaining only a finite number of equations. The resulting systems, however, will not be closed, because the highest order moments, appearing as flux(es) in the last equation(s), and also the production terms on the right-hand side remain undetermined. In the spirit of continuum physics, *extended thermodynamics* closes these systems by postulating that the highest order moments and the production terms are related to the lower order moments by constitutive equations that are determined by requiring that all smooth solutions of the system satisfy identically a certain inequality, akin to the Clausius-Duhem inequality. This induces a companion balance law which renders the system symmetrizable and thereby hyperbolic. The principle of material frame indifference should also be observed by the constitutive relations.

To see how the program works in practice, let us construct a truncation of (3.3.53) with state vector $U = (\rho, v, p, \sigma, q)$, which has dimension 13, as σ is symmetric and traceless. For that purpose, we retain the first three of the equations of (3.3.53), for a total of 10 independent scalar equations, and also extract 3 equations from the fourth equation of (3.3.53) by contracting two of the indices. By virtue of (3.3.54), (3.3.55), (3.3.56), (3.3.57), (3.3.58) and since P, P_i and P_{ii} vanish, we end up with the system

$$(3.3.60) \quad \left\{ \begin{array}{l} \partial_t \rho + \partial_j(\rho v_j) = 0 \\ \partial_t(\rho v_i) + \partial_j(\rho v_i v_j + p\delta_{ij} - \sigma_{ij}) = 0 \\ \partial_t(\rho\varepsilon + \frac{1}{2}\rho|v|^2) + \partial_k\{(\rho\varepsilon + \frac{1}{2}\rho|v|^2 + p)v_k - \sigma_{kj}v_j + q_k\} = 0 \\ \partial_t(\rho v_i v_j - \frac{1}{3}\rho|v|^2\delta_{ij} - \sigma_{ij}) + \partial_k(F_{ijk} - \frac{1}{3}F_{\ell\ell k}\delta_{ij}) = P_{ij}/\varepsilon \\ \partial_t\{(\rho\varepsilon + \frac{1}{2}\rho|v|^2 + p)v_k - \sigma_{kj}v_j + q_k\} + \frac{1}{2}\partial_i F_{jjik} = \frac{1}{2}P_{iik}/\varepsilon \end{array} \right.$$

This system can be closed by postulating that $F_{ijk}, F_{jjik}, P_{ij}$ and P_{iik} are functions of the state vector $U = (\rho, v, p, \sigma, q)$, which are determined by requiring that all smooth solutions satisfy identically an inequality

$$(3.3.61) \quad \partial_t \varphi + \partial_i \psi_i \leq 0,$$

where φ and ψ_i are (unspecified) functions of U , and $\varphi(U)$ is convex. After a lengthy calculation (see the references cited in Section 3.4), one obtains complicated albeit quite explicit constitutive relations:

$$(3.3.62) \quad F_{ijk} = \rho v_i v_j v_k + (p v_k + \frac{2}{3} q_k) \delta_{ij} + (p v_i + \frac{2}{3} q_i) \delta_{jk} + (p v_j + \frac{2}{3} q_j) \delta_{ik},$$

$$(3.3.63) \quad F_{jjk} = (\rho |v|^2 + 7p) v_i v_k + (p \delta_{ik} - \sigma_{ik}) |v|^2 - \sigma_{ij} v_j v_k \\ - \sigma_{kj} v_j v_i + \frac{14}{5} (q_i v_k + q_k v_i) + \frac{4}{5} q_j v_j \delta_{ik} + \frac{p}{\rho} (5p \delta_{ik} - 7\sigma_{ik}),$$

$$(3.3.64) \quad P_{ij} = \tau_0 \sigma_{ij}, \quad P_{ik} = 2\tau_0 \sigma_{ki} v_i - \tau_1 q_k.$$

To complete the picture, p , τ_0 and τ_1 must be specified as functions of (ρ, θ) .

The special vector $U^* = B(U)$, in the notation of Section 1.5, that symmetrizes the system has components

$$(3.3.65) \quad U^* = \frac{1}{\theta} \begin{pmatrix} \frac{5p}{2\rho} - \theta s - \frac{1}{2} |v|^2 + \frac{1}{2p} \sigma_{ij} v_i v_j - \frac{\rho}{5p^2} q_i v_i |v|^2 \\ v_i - \frac{1}{p} \sigma_{ij} v_j + \frac{\rho}{5p^2} (|v|^2 q_i + 2q_j v_j v_i) \\ -1 + \frac{2\rho}{3p^2} q_k v_k \\ -\frac{1}{2p} \sigma_{ij} - \frac{\rho}{5p^2} (v_i q_j + v_j q_i - \frac{2}{3} v_k q_k \delta_{ij}) \\ \frac{\rho}{5p^2} q_i \end{pmatrix}$$

In particular, as explained in Section 1.5, truncating the system (3.3.60) by dropping the last two equations should be paired with “freezing” the last two components of U^* , i.e., by setting $q = 0$ and $\sigma = 0$. In that case, the system of the first three equations of (3.3.60) reduces to the system (3.3.29), in the particular situation where $b = 0$, $r = 0$ and $\rho \varepsilon$ and p are related by (3.3.59). If one interprets (ρ, v, p) as the basic state variables and (σ, q) as internal state variables, as explained in Section 2.8, then (3.3.29) becomes the relaxed form of the system (3.3.60).

3.3.8 Nonlinear Electrodynamics:

Another rich source of interesting systems of hyperbolic balance laws is electromagnetism. The underlying system consists of Maxwell’s equations

$$(3.3.66) \quad \begin{cases} \partial_t B = -\operatorname{curl} E \\ \partial_t D = \operatorname{curl} H - J \end{cases}$$

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We now linearize the 13 moment system

about $\underline{v}=0, \theta=\theta_0, \rho=\rho_0$, i.e.

write

$$\underline{v} = 0 + \underline{v}, \theta = \theta_0 + \bar{\theta}, \rho = \rho_0 + \bar{\rho},$$

substitute into the system, and retain only

linear terms. This yields

$$\partial_t \rho + \partial_j (\rho_0 v_j) = 0$$

$$\partial_t (\rho_0 v_i) + \partial_j (p \delta_{ij} - \sigma_{ij}) = 0$$

$$\partial_t \left(\frac{3}{2} p \right) + \cancel{\partial_j (\rho_0 v_j)}$$

$$+ \partial_k \left(\frac{5}{2} \rho_0 v_k \cancel{\sigma_{ij}} + q_k \right) = 0$$

$$\partial_t (-\sigma_{ij}) + \partial_k \left((\rho_0 v_k + \frac{2}{5} q_k) \delta_{ij} \right)$$

$$+ (\rho_0 v_i + \frac{2}{5} q_i) \delta_{jk} + (\rho_0 v_j + \frac{2}{5} q_j) \delta_{ik}$$

$$- \frac{5}{3} (\rho_0 v_k + \frac{2}{5} q_k) \delta_{ij} = \frac{\rho_0 \sigma_{ij}}{\epsilon}$$

$$\cancel{\partial_t \left(\frac{3}{2} p \right)}$$

$$\cancel{\partial_k \left(\frac{5}{2} \rho_0 v_k + q_k \right)}$$

$$\partial_t \left(\frac{5}{2} p_0 v_k + q_k \right) + \frac{1}{2} \partial_i \left(\cancel{2 \frac{p_0 p}{\rho_0}} \delta_{ik} + \frac{p_0^2}{\rho_0^2} \delta_{ik} - \tau \sigma_{ik} \right) = \frac{\tau_0}{2} \frac{q_k}{\epsilon}$$

We can rewrite the ~~last two equations~~ next to last equation as

$$-\partial_t \sigma_{ij} + \partial_k \left(\frac{2}{3} (p_0 v_k + \frac{2}{5} q_k) \delta_{ij} + (p_0 v_i + \frac{2}{5} q_i) \delta_{jk} + (p_0 v_j + \frac{2}{5} q_j) \delta_{ik} \right) = \frac{\tau_0}{\epsilon} \sigma_{ij}.$$

Let us choose the linearization of

$$p = R \rho \theta \quad \text{i.e.}$$

$$p = \cancel{R} R (\rho_0 \theta + \rho \theta_0), \quad p_0 = R \rho_0 \theta_0.$$

~~with $R = \rho_0 = 1$, $\rho = 1$ i.e. $p = \theta + \rho$.~~

~~(This can be done by a rescaling.)~~

let us set for convenience $R=1$, $\rho_0=1$, $\theta_0=1$,

so that $p = \rho + \theta$, $p_0 = 1$

In one space dimension our equations are

$$\partial_t \rho + \partial_x v = 0$$

$$\partial_t v + \partial_x p = \partial_x \sigma$$

$$\frac{3}{2} \partial_t p + \partial_x \left(\frac{5}{2} v \right) = -\partial_x q$$

$$-\partial_t \sigma + \frac{4}{3} \partial_x \left(v + \frac{2}{5} q \right) = \frac{c_0}{\epsilon} \sigma$$

$$\partial_t \left(\frac{5}{2} v + q \right) + \frac{1}{2} \partial_x \left(10p - 5q - 7\sigma \right) = -\frac{c_1}{2\epsilon} q$$

Use the second equation to see

$$\frac{5}{2} \partial_t v + \frac{5}{2} \partial_x p = \frac{5}{2} \partial_x \sigma$$

and then the last equation becomes

$$\partial_t q + \partial_x \left(\frac{5}{2} p - \frac{5}{2} q - \frac{7}{2} \sigma + \frac{5}{2} \sigma \right) = -\frac{c_1}{2\epsilon} q$$

or

$$\partial_t q + \partial_x \left(\frac{5}{2} (p - q) - \sigma \right) = -\frac{c_1}{2\epsilon} q$$

In summary the linearized one dimensional system is

$$\left. \begin{aligned} \partial_t \rho + \partial_x v &= 0 \\ \partial_t v + \partial_x p &= \partial_x \sigma \\ \partial_t p + \frac{5}{3} \partial_x v &= -\frac{3}{2} q_x \\ -\partial_t \sigma - \frac{4}{3} \partial_x \left(v + \frac{2}{5} q \right) &= -\frac{7_0}{\Sigma E} \sigma \end{aligned} \right\}$$

$$\partial_t q + \partial_x \left(\frac{5}{2} (p - \rho) - \sigma \right) = -\frac{7_1}{\Sigma E} q$$

This exactly the same one dimensional system that we would obtain from Grad's closure rule.

To keep the computations simple let us consider an even simpler subset of these equations by formally setting the heat flux $q \equiv 0$

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(35)

$$\partial_t v + \partial_x p = \partial_x \sigma$$

(2.4)

$$\partial_t p + \frac{5}{3} \partial_x v = 0$$

(2.5)

$$\partial_t \sigma - \frac{4}{3} \partial_x v = -\frac{\sigma}{\epsilon}$$

(2.6)

Our goal is now to apply
the Chapman-Enskog procedure to this
simple set of three partial differential equations.

Write

$$\vec{v}_{CE} = \epsilon \sigma^{(0)} + \epsilon^2 \sigma^{(1)} + \epsilon^3 \sigma^{(2)} + \dots \quad (2.7)$$

where $\sigma^{(n)}$ depends on the current values of

p, v and their space derivatives. Substitute

(2.7) into (2.4) - (2.6) to see

$$\partial_t v + \partial_x p = \partial_x \left(\epsilon \sigma^{(0)} + \epsilon^2 \sigma^{(1)} + \epsilon^3 \sigma^{(2)} + \dots \right) \quad (2.4)_\epsilon$$

$$\partial_t p + \frac{5}{3} \partial_x v = 0 \quad (2.5)_\epsilon$$

$$\partial_t \left(\epsilon \sigma^{(0)} + \epsilon^2 \sigma^{(1)} + \epsilon^3 \sigma^{(2)} + \dots \right) - \frac{4}{3} \partial_x v = - \left(\sigma^{(0)} + \epsilon \sigma^{(1)} + \epsilon^2 \sigma^{(2)} + \dots \right) \quad (2.6)_\epsilon$$

$$\Rightarrow \boxed{\sigma^{(0)} = \frac{4}{3} \partial_x v} \quad (2.8)$$

Insert (2.8) into (2.4)_ε, (2.5)_ε to see

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$$\partial_t v + \partial_x p = \partial_x \left(\frac{4}{3} \epsilon \partial_x v + \epsilon^2 \sigma^{(1)} + \epsilon^3 \sigma^{(2)} + \dots \right) \quad (2.4\epsilon)$$

$$\partial_t \left(\frac{4}{3} \epsilon \partial_x v + \epsilon^2 \sigma^{(1)} + \epsilon^3 \sigma^{(2)} + \dots \right) = - \left(\epsilon \sigma^{(1)} + \epsilon^2 \sigma^{(2)} + \dots \right) \quad (2.6\epsilon)$$

But by (2.4\epsilon)

$$\partial_t \partial_x v = \partial_x \partial_t v$$

$$= \partial_x \left\{ -\partial_x p + \partial_x \left(\epsilon \frac{4}{3} \partial_x v + \epsilon^2 \sigma^{(1)} + \dots \right) \right\}$$

$$= -\partial_x p + \partial_x \left(\epsilon \frac{4}{3} \partial_x v \right)$$

$$+ \partial_x^3 \epsilon^2 \sigma^{(1)} + \dots$$

So that (2.6\epsilon) becomes

$$\frac{4}{3} \epsilon \left(-\partial_x p + \frac{4}{3} \epsilon \partial_x^2 v + \epsilon^2 \partial_x^3 \sigma^{(1)} + \dots \right) + \partial_t \left(\epsilon^2 \sigma^{(1)} + \epsilon^3 \sigma^{(2)} + \dots \right)$$

$$= -\epsilon \sigma^{(1)} - \epsilon^2 \sigma^{(2)} - \epsilon^3 \sigma^{(3)} + \dots \quad (2.9)$$

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4)

Hence balance $O(\epsilon)$:

$$\sigma^{(1)} = \frac{4}{3} \partial_{xxx} p \quad (30)$$

and balance $O(\epsilon^2)$:

$$\frac{4}{3} \left(\frac{4}{3} \right) \partial_{xxx} v + \partial_t \sigma^{(1)} = -\sigma^{(2)} \quad (31)$$

But

$$\partial_t \sigma^{(1)} = \frac{4}{3} \partial_{xx} \partial_t p \quad \text{by (30)}$$

$$= \frac{4}{3} \partial_{xx} \left(-\frac{5}{3} \partial_{xx} v \right)$$

$$\partial_t \sigma^{(1)} = -\frac{20}{3 \cdot 3} \partial_{xxxx} v$$

Hence by (31)

$$\frac{16}{3 \cdot 3} \partial_{xxxx} v - \frac{20}{3 \cdot 3} \partial_{xxxx} v = -\sigma^{(2)}$$

and

$$\sigma^{(2)} = \frac{4}{3} \left(\frac{1}{3} \right) \partial_{xxxx} v \quad (32)$$

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Hence

$$\sigma_{CE} = \epsilon \left(\frac{4}{3} \partial_x v + \epsilon \frac{4}{3} \partial_{xx} p + \epsilon^2 \frac{4}{3} \left(\frac{1}{3} \right) \partial_{xxx} v + \dots \right)$$

$$\sigma_{CE} = \frac{4}{3} \epsilon \left(\partial_x v + \epsilon \partial_{xx} p + \frac{\epsilon^2}{3} \partial_{xxx} v + \dots \right) \quad (32)$$

and our PDE are

$$\partial_t v + \partial_x p = \frac{4}{3} \epsilon \left(\partial_x v + \epsilon \partial_{xx} p + \frac{\epsilon^2}{3} \partial_{xxx} v + \dots \right)$$

$$\partial_t p + \frac{5}{3} \partial_x v = 0 \quad (33)$$

~~by $\partial_t v + \partial_x p = \dots$~~

TRUNCATION AT $O(1)$:

$$\left\{ \begin{array}{l} \partial_t v + \partial_x p = 0 \\ \partial_t p + \frac{5}{3} \partial_x v = 0 \end{array} \right. \quad \underline{\text{"Euler"}}$$

TRUNCATION AT $O(\epsilon)$:

$$\left\{ \begin{array}{l} \partial_t v + \partial_x p = \frac{4}{3} \epsilon \partial_{xx} v \\ \partial_t p + \frac{5}{3} \partial_x v = 0 \end{array} \right. \quad \underline{\text{"NAVIER-STOKES"}}$$

TRUNCATION AT $O(\epsilon^2)$:

$$\left\{ \begin{array}{l} \partial_t v + \partial_x p = \frac{4}{3} \epsilon \left(\partial_{xx} v + \epsilon \partial_{xxx} p \right) \\ \partial_t p + \frac{5}{3} \partial_x v = 0 \end{array} \right. \quad \underline{\text{"BURNETT"}}$$

TRUNCATION AT $O(\epsilon^3)$

$$\left\{ \begin{array}{l} \partial_t v + \partial_x p = \frac{4}{3} \epsilon \left(\partial_{xx} v + \epsilon \partial_{xxx} p + \frac{\epsilon^2}{3} \partial_{xxxx} v \right) \\ \partial_t p + \frac{5}{3} \partial_x v = 0 \end{array} \right. \quad \underline{\text{"SUPER-BURNETT"}}$$

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STABILITY OF REST STATE

PLUG IN

$$\begin{cases} v = e^{\omega t} e^{ikx} V \\ p = e^{\omega t} e^{ikx} P \end{cases}$$

EULER

$$\begin{cases} \omega V + \kappa P = 0 \\ \omega P + \frac{5}{3} i \kappa V = 0 \end{cases}$$

\Rightarrow

$$\begin{aligned} \omega^2 V + i \kappa \omega P &= 0 \Rightarrow \\ \omega^2 V + \kappa \left(-\frac{5}{3} i \kappa V \right) &= 0 \\ \left(\omega^2 + \frac{5}{3} \kappa^2 \right) V &= 0 \end{aligned}$$

$$\omega^2 = -\frac{5}{3} \kappa^2$$

NEUTRAL STABILITY
AT "EULER" LEVEL

$$\omega = \pm i \left(\frac{5}{3} \right)^{1/2} \kappa$$

NAYIER - STOKES

$$\omega V + \kappa P = -\frac{4}{3} \epsilon \kappa^2 \omega V$$

$$\begin{aligned} \omega^2 V + i \kappa \omega P &= \\ -\frac{4}{3} \epsilon \kappa^2 \omega V & \end{aligned}$$

$$\omega P + \frac{5}{3} i \kappa V = 0$$

$$\Rightarrow \omega^2 V + i \kappa \left(-\frac{5}{3} i \kappa V \right) = -\frac{4}{3} \epsilon \kappa^2 \omega V$$

$$\left(\omega^2 + \frac{5}{3} \kappa^2 + \frac{4}{3} \epsilon \kappa^2 \omega \right) V = 0$$

QUADRATIC FORMULA \Rightarrow

$$\omega = \frac{-\frac{4}{3} \epsilon \kappa^2 \pm \left(\frac{16}{9} \epsilon^2 \kappa^4 - 4 \cdot \frac{5}{3} \kappa^2 \right)^{1/2}}{2}$$

$$\omega = -\frac{2}{3} \epsilon \kappa^2 \pm \left(\frac{4}{9} \epsilon^2 \kappa^4 - \frac{5}{3} \kappa^2 \right)^{1/2}$$

$$= -\frac{2}{3} \epsilon \kappa^2 \pm \kappa \left(\frac{4}{9} \epsilon^2 \kappa^2 - \frac{5}{3} \right)^{1/2}$$

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$$\left\{ \begin{array}{l} \frac{4}{9} \varepsilon^2 k^2 - \frac{5}{3} < 0 \\ \text{2 complex roots} \\ \text{Real parts} < 0 \end{array} \right.$$

$$\left\{ \begin{array}{l} \frac{4}{9} \varepsilon^2 k^2 - \frac{5}{3} \geq 0 \\ \text{2 real roots} \\ \text{both } \underline{\text{negative}} \end{array} \right.$$

EXPONENTIAL ASYMPTOTIC STABILITY AT
"NAVIER - STOKES" LEVEL

BURNETT

$$\omega V + \nu k P = -\frac{4}{3} \varepsilon k^2 \bar{V} + \frac{4}{3} \varepsilon^2 k^3 \bar{P}$$

$$\omega P + \frac{5}{3} \nu k \bar{V} = 0$$

$$\omega^2 V + \nu k \omega P = -\frac{4}{3} \varepsilon k^2 \omega \bar{V} - \frac{4}{3} \varepsilon^2 \nu k^3 \omega \bar{P}$$

$$\omega^2 V + \nu k \left(-\frac{5}{3} \nu k \bar{V} \right) = -\frac{4}{3} \varepsilon k^2 \omega \bar{V} + \frac{4}{3} \frac{5}{3} \varepsilon^2 \nu k^3 \frac{5}{3} \nu k \bar{V}$$

$$\omega^2 V + \frac{5}{3} \nu k^2 \bar{V} + \frac{4}{3} \varepsilon k^2 \omega \bar{V} + \frac{4}{3} \frac{5}{3} \varepsilon^2 \nu k^4 \bar{V} = 0$$

$$\left(\omega^2 + \frac{4}{3} \varepsilon k^2 \omega + \frac{5}{3} \nu k^2 + \frac{4}{3} \frac{5}{3} \varepsilon^2 \nu k^4 \right) \bar{V} = 0$$

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$$\omega = -\frac{2}{3} k^2 \varepsilon \pm \frac{1}{2} \left(\frac{16}{9} \varepsilon^2 k^4 - 4 \left(\frac{5}{3} k^2 + \frac{20}{9} \varepsilon^2 k^4 \right) \right)^{1/2}$$

$$\omega = -\frac{2}{3} k^2 \varepsilon \pm \left(\frac{4}{9} \varepsilon^2 k^4 - \left(\frac{5}{3} k^2 + \frac{20}{9} \varepsilon^2 k^4 \right) \right)^{1/2}$$

$$\omega = -\frac{2}{3} k^2 \varepsilon \pm \left(-\frac{16}{9} \varepsilon^2 k^4 - \frac{5}{3} k^2 \right)^{1/2}$$

$$\omega = -\frac{2}{3} k^2 \varepsilon \pm \frac{i|k|}{3} \left(+16 \varepsilon^2 k^2 + 15 \right)^{1/2}$$

2 complex roots, Real parts < 0

EXPONENTIAL ASYMPTOTIC STABILITY AT

"BURNETT LEVEL"

$$\omega V + i k P = -\frac{4}{3} \epsilon^2 k^2 V + \frac{4}{3} \epsilon^2 i^3 k^3 P - \frac{4}{3} \frac{1}{3} \epsilon^4 k^4 V$$

$$\omega P + \frac{5}{3} i k V = 0$$

$$\omega^2 V + i k P \omega = -\frac{4}{3} \epsilon^2 k^2 \omega V + \frac{4}{3} \epsilon^2 i k^3 \omega P + \frac{4}{3} \frac{1}{3} \epsilon^4 k^4 \omega V$$

$$\omega = \frac{2}{9} k^2 (k^2 - 3) \pm \frac{i}{9} |k| \sqrt{4 k^6 - 24 k^4 - 72 k^2 - 135}$$

$$k^2 > 3 \quad \Rightarrow \quad \frac{2}{9} k^2 (k^2 - 3) > 0$$

large k^2 2 complex roots
 Real parts > 0

E exponentially unstable at
Super-Burnett order